

Package: viewscape (via r-universe)

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Type Package

Title Viewscape Analysis

Version 2.0.1

Description A collection of functions to make R a more effective viewscape analysis tool for calculating viewscape metrics based on computing the viewable area for given a point/multiple viewpoints and a digital elevation model. The method of calculating viewscape metrics implemented in this package are based on the work of Tabrizian et al. (2020) [doi:10.1016/j.landurbplan.2019.103704](https://doi.org/10.1016/j.landurbplan.2019.103704). The algorithm of computing viewshed is based on the work of Franklin & Ray. (1994) <https://citeseerx.ist.psu.edu/document?repid=rep1&type=pdf&doi=555780f6f5d7e537eb1edb28862c86d1519af2be>.

URL <https://github.com/land-info-lab/viewscope>

BugReports <https://github.com/land-info-lab/viewscope/issues>

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Contents

calculate_diversity	2
calculate_feature	3
calculate_viewmetrics	4
compute_viewshed	6
fov_mask	8
Viewshed-class	9
visualize_viewshed	9
visual_magnitude	10

Index	12
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calculate_diversity	<i>calculate_diversity</i>
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Description

The `calculate_diversity` function is designed to calculate landscape diversity metrics within a viewshed. It takes as input a land cover raster, a viewshed object representing the observer's line of sight, and an optional parameter to compute class proportions.

Usage

```
calculate_diversity(viewshed, land, proportion = FALSE)
```

Arguments

<code>viewshed</code>	Viewshed object.
<code>land</code>	Raster. The raster of land use/land cover representing different land use/cover classes.
<code>proportion</code>	logical (Optional), indicating whether to return class proportions along with the Shannon Diversity Index (SDI). (default is FALSE).

Value

List. a list containing the Shannon Diversity Index (SDI) and, if the `proportion` parameter is set to TRUE, a table of class proportions within the viewshed.

Examples

```
library(viewscape)
# Load a viewpoint
test_viewpoint <- sf::read_sf(system.file("test_viewpoint.shp", package = "viewscape"))
# load dsm raster
dsm <- terra::rast(system.file("test_dsm.tif", package = "viewscape"))
#Compute viewshed
output <- viewscape::compute_viewshed(dsm = dsm,
                                       viewpoints = test_viewpoint,
                                       offset_viewpoint = 6, r = 1600)

# load landuse raster
test_landuse <- terra::rast(system.file("test_landuse.tif",
                                       package = "viewscape"))

diversity <- viewscape::calculate_diversity(output,
                                           test_landuse)
```

calculate_feature *calculate_feature*

Description

The `calculate_feature` function is designed to extract specific feature-related information within a viewshed. It allows you to compute the proportion of the feature that is present in the viewshed.

Usage

```
calculate_feature(viewshed, feature, type, exclude_value)
```

Arguments

<code>viewshed</code>	Viewshed object.
<code>feature</code>	Raster. Land cover or land use
<code>type</code>	Numeric. The input type of land cover raster. <code>type=1</code> : percentage raster (that represents the percentage of area in each cell). <code>type=2</code> : binary raster (that only uses two values to represent whether the feature exists in each cell).
<code>exclude_value</code>	Numeric. the value of those cells need to be excluded in the analysis. If <code>type = 2</code> , <code>exclude_value</code> is required.

Value

Numeric. The canopy area in the viewshed.

Examples

```
library(viewscape)
# Load a viewpoint
test_viewpoint <- sf::read_sf(system.file("test_viewpoint.shp", package = "viewscape"))
# load dsm raster
dsm <- terra::rast(system.file("test_dsm.tif", package = "viewscape"))
#Compute viewshed
viewshed <- viewscape::compute_viewshed(dsm = dsm,
                                         viewpoints = test_viewpoint,
                                         offset_viewpoint = 6)

# load canopy raster
test_canopy <- terra::rast(system.file("test_canopy.tif",
                                       package = "viewscape"))

# calculate the percentage of canopy coverage
test_canopy_proportion <- viewscape::calculate_feature(viewshed = viewshed,
                                                       feature = test_canopy,
                                                       type = 2,
                                                       exclude_value = 0)
```

calculate_viewmetrics *calculate_viewmetrics*

Description

The `calculate_viewmetrics` function is designed to compute a set of configuration metrics based on a given viewshed object and optionally, digital surface models (DSM) and digital terrain models (DTM) for terrain analysis. The function calculates various metrics that describe the visibility characteristics of a landscape from a specific viewpoint. The metrics include:

1. Extent: The total area of the viewshed, calculated as the number of visible grid cells multiplied by the grid resolution
2. Depth: The furthest visible distance within the viewshed from the viewpoint
3. Vdepth: The standard deviation of distances to visible points, providing a measure of the variation in visible distances
4. Horizontal: The total visible horizontal or terrestrial area within the viewshed
5. Relief: The standard deviation of elevations of the visible ground surface
6. Skyline: The standard deviation of the vertical viewscape, including visible canopy and buildings, when specified
7. Number of patches: Visible fragmentation measured by total visible patches with the viewscape
8. Mean shape index: Visible patchiness based on average perimeter-to-area ratio for all viewscape patches (vegetation and building)
9. Edge density: A measure of visible complexity based on the length of patch edges per unit area
10. Patch size: Total average size of a patches over the entire viewscape area

11. Patch density: Visible landscape granularity based on measuring patch density
12. Shannon diversity index: The abundance and evenness of land cover/use in a viewshed
13. Proportion of object: Proportion of a single type of land use or cover in a viewshed

Usage

```
calculate_viewmetrics(viewshed, dsm, dtm, masks = list())
```

Arguments

viewshed	Viewshed object.
dsm	Raster, Digital Surface Model for the calculation of
dtm	Raster, Digital Terrain Model
masks	List, a list including rasters of canopy and building footprints. For example of canopy raster, the value for cells without canopy should be 0 and the value for cells with canopy can be any number.

Value

List

References

Tabrizian, P., Baran, P.K., Berkel, D.B., Mitásová, H., & Meentemeyer, R.K. (2020). Modeling restorative potential of urban environments by coupling viewscape analysis of lidar data with experiments in immersive virtual environments. *Landscape and Urban Planning*, 195, 103704.

Examples

```
# Load in DSM
test_dsm <- terra::rast(system.file("test_dsm.tif",
                                   package = "viewscape"))

# Load DTM
test_dtm <- terra::rast(system.file("test_dtm.tif",
                                   package = "viewscape"))

# Load canopy raster
test_canopy <- terra::rast(system.file("test_canopy.tif",
                                       package = "viewscape"))

# Load building footprints raster
test_building <- terra::rast(system.file("test_building.tif",
                                       package = "viewscape"))

# Load in the viewpoint
test_viewpoint <- sf::read_sf(system.file("test_viewpoint.shp",
                                         package = "viewscape"))

# Compute viewshed
output <- viewscape::compute_viewshed(dsm = test_dsm,
```

```

viewpoints = test_viewpoint,
offset_viewpoint = 6, r = 1600)

# calculate metrics given the viewshed, canopy, and building footprints
test_metrics <- viewscape::calculate_viewmetrics(output,
                                                test_dsm,
                                                test_dtm,
                                                list(test_canopy, test_building))

```

```
compute_viewshed      compute_viewshed
```

Description

The `compute_viewshed` function is designed for computing viewsheds, which are areas visible from specific viewpoints, based on a Digital Surface Model (DSM). It provides flexibility for single or multi-viewpoint analyses and allows options for parallel processing, raster output, and plotting.

Usage

```

compute_viewshed(
  dsm,
  viewpoints,
  offset_viewpoint = 1.7,
  offset_height = 0,
  r = NULL,
  refraction_factor = 0.13,
  method = "plane",
  parallel = FALSE,
  workers = 1,
  raster = FALSE,
  plot = FALSE
)

```

Arguments

<code>dsm</code>	Raster, the digital surface model/digital elevation model
<code>viewpoints</code>	sf point(s) or vector including x,y coordinates of a viewpoint or a matrix including several viewpoints with x,y coordinates
<code>offset_viewpoint</code>	numeric, setting the height of the viewpoint. (default is 1.7 meters).
<code>offset_height</code>	numeric, setting the height of positions that a given viewpoint will look at. (default is 0)
<code>r</code>	Numeric (optional), setting the radius for viewshed analysis. (The default is 1000m/3281ft)

refraction_factor	Number, indicating the refraction factor. The refraction factor adjusts the effect of atmospheric refraction on the apparent curvature of the Earth. In most standard applications, a refraction factor of 0.13 is used, and so does this function. However, the appropriate refraction factor may vary depending on environmental conditions.
method	Character, The algorithm for computing a viewshed: "plane" and "los" (see details). "plane" is used as default.
parallel	Logical, (default is FALSE) indicating if parallel computing should be used to compute viewsheds of multiview points. When it is TRUE, arguments 'raster' and 'plot' are ignored
workers	Numeric, indicating the number of CPU cores that will be used for parallel computing. It is required if 'parallel' is 'TRUE'.
raster	Logical, (default is FALSE) if it is TRUE, the raster of viewshed will be returned. The default is FALSE
plot	Logical, (default is FALSE) if it is TRUE, the raster of viewshed will be displayed

Details

For method, "plane" is the reference plane algorithm introduced by Wang et al. (2000) and "los" is the line of sight algorithm (Franklin & Ray, 1994). The reference plane algorithm can be more time-efficient than the line of sight algorithm, whereas the accuracy of the line of sight is better.

Value

Raster or list. For single-viewpoint analysis, the function returns either a raster (raster is TRUE) or a viewshed object. Value 1 means visible while value 0 means invisible. For multi-viewpoint analysis, a list of viewsheds is returned.

References

Franklin, W. R., & Ray, C. (1994, May). Higher isn't necessarily better: Visibility algorithms and experiments. In *Advances in GIS research: sixth international symposium on spatial data handling* (Vol. 2, pp. 751-770). Edinburgh: Taylor & Francis.

Wang, J., Robinson, G. J., & White, K. (2000). Generating viewsheds without using sightlines. *Photogrammetric engineering and remote sensing*, 66(1), 87-90.

See Also

[fov_mask\(\)](#) [visual_magnitude\(\)](#)

Examples

```
# Load a viewpoint
test_viewpoint <- sf::read_sf(system.file("test_viewpoint.shp", package = "viewscape"))
# load dsm raster
dsm <- terra::rast(system.file("test_dsm.tif", package = "viewscape"))
```

```
#Compute viewshed
output <- viewscape::compute_viewshed(dsm = dsm,
                                     viewpoints = test_viewpoint,
                                     offset_viewpoint = 6, r = 1600)
```

fov_mask	<i>fov_mask</i>
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Description

The `fov_mask` function is designed to subset a viewshed based on its viewpoint and the field of view

Usage

```
fov_mask(viewshed, fov)
```

Arguments

<code>viewshed</code>	viewshed object, generated by <code>compute_viewshed()</code>
<code>fov</code>	Vector, specifying the field of view with two angles in degree (e.g. <code>c(10,100)</code>) for masking a viewshed based on its viewpoints. See details.

Details

For defining the field of view ('fov'), angles range from 0 to 360 degrees, with 0 inclusive and 360 exclusive. The initial angle must be smaller than the terminal angle in the sequence `c(a,b)` ($a < b$). To capture the northeast quadrant of a viewshed, one would use `c(0,90)`, while the eastern quadrant would be delineated by `c(45,315)` as shown below:

135	90	45
180	v	0
225	270	315

Here, 'v' represents the viewpoint, with angles measured counterclockwise from due north.

Value

viewshed object

See Also

[compute_viewshed\(\)](#)

Examples

```

# Load a viewpoint
test_viewpoint <- sf::read_sf(system.file("test_viewpoint.shp", package = "viewscape"))
# load dsm raster
dsm <- terra::rast(system.file("test_dsm.tif", package = "viewscape"))
# Compute viewshed
viewshed <- viewscape::compute_viewshed(dsm,
                                         viewpoints = test_viewpoint,
                                         offset_viewpoint = 6)
# subset viewshed using the field of view
out <- viewscape::fov_mask(viewshed, c(40,160))

```

Viewshed-class	<i>An S4 class to represent the viewshed</i>
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Description

A viewshed object contains a 'matrix' of visible and invisible area, resolution, extent, and crs

Slots

visible matrix
 resolution vector
 extent numeric
 crs character

visualize_viewshed	<i>visualize_viewshed</i>
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Description

The visualize_viewshed function is designed for the visualization of a viewshed analysis, providing users with various options for visualizing the results. The function works with a viewshed object and offers multiple plotting and output types.

Usage

```
visualize_viewshed(viewshed, plottype = "", outputtype = "")
```

Arguments

viewshed	Viewshed object
plottype	Character, specifying the type of visualization ("polygon" or "raster").
outputtype	Character, specifying the type of output object ("raster" or "polygon").

Value

Visualized viewshed as either a raster or polygon object, depending on the outputtype specified.

Examples

```
# Load a viewpoint
test_viewpoint <- sf::read_sf(system.file("test_viewpoint.shp", package = "viewscape"))
# load dsm raster
dsm <- terra::rast(system.file("test_dsm.tif", package = "viewscape"))
#Compute viewshed
viewshed <- compute_viewshed(dsm = dsm,
                             viewpoints = test_viewpoint,
                             offset_viewpoint = 6)
# Visualize the viewshed as polygons
visualize_viewshed(viewshed, plottype = "polygon")
# Visualize the viewshed as a raster
visualize_viewshed(viewshed, plottype = "raster")
# Get the visualized viewshed as a polygon object
polygon_viewshed <- visualize_viewshed(viewshed,
                                       plottype = "polygon",
                                       outputtype = "polygon")
```

visual_magnitude

visual_magnitude

Description

This function is still in progress. Visual Magnitude quantifies the extent of a visible region as perceived by an observer. It is derived from the surface's slope and angle features, alongside the observer's relative distance from the area (Chamberlain & Meitner).

Usage

```
visual_magnitude(viewshed, dsm)
```

Arguments

viewshed	Viewshed object.
dsm	Raster, the digital surface / elevation model

Value

SpatRaster

References

Chamberlain, B. C., & Meitner, M. J. (2013). A route-based visibility analysis for landscape management. *Landscape and Urban Planning*, 111, 13-24.

See Also[compute_viewshed\(\)](#)**Examples**

```
# Load a viewpoint
test_viewpoint <- sf::read_sf(system.file("test_viewpoint.shp", package = "viewscape"))
# load dsm raster
dsm <- terra::rast(system.file("test_dsm.tif", package = "viewscape"))
# Compute viewshed
viewshed <- viewscape::compute_viewshed(dsm = dsm,
                                       viewpoints = test_viewpoint,
                                       offset_viewpoint = 6)

# Compute visual magnitude
vm <- viewscape::visual_magnitude(viewshed, dsm)
```

Index

`calculate_diversity`, [2](#)
`calculate_feature`, [3](#)
`calculate_viewmetrics`, [4](#)
`compute_viewshed`, [6](#)
`compute_viewshed()`, [8](#), [11](#)

`fov_mask`, [8](#)
`fov_mask()`, [7](#)

`Viewshed`-class, [9](#)
`visual_magnitude`, [10](#)
`visual_magnitude()`, [7](#)
`visualize_viewshed`, [9](#)